

Control Orchestration Protocol (COP)

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- Website:<http://opensourcesdn.org/projects/project-englewood/>
- Organization:STRAUSS project
- Contact:
- Repository:
- License:
- Status:Active

Project Description: The Control Orchestration Protocol (COP) abstracts a set of control plane functions used by an SDN Controller, allowing the interworking of heterogeneous control plane paradigms (i.e., OpenFlow, GMPLS/PCE).



- Link scientific paper(s)
- Link whitepaper(s)
- Link video(s)
- Link presentation(s)
- Link further resources